The Solow Growth Model Econ 504

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The first ingredient of a dynamic model is the description of the *time horizon* and the set of *commodities*.

In the original Solow model, time is continuous and the horizon is infinite. Without loss of generality assume that time is indexed by t in $[0, \infty)$.

At each point in time, there is only one final good

The good is produced via the *aggregate production function*:

$$Y = F(K, AL)$$

Here Y, A, K, and L denote output, labor productivity, capital, and labor, and are functions of time (i.e. we should really write Y(t) and so on, but we omit time arguments when not needed). The product AL is called *effective labor*.

The function F has neoclassical properties:

- F is continuously differentiable, strictly increasing, strictly concave
- F has constant returns to scale

A key example is the Cobb Douglas function:

$$F(K, AL) = K^{\alpha}(AL)^{1-\alpha}, 0 < \alpha < 1$$

Exercise: Show that the Cobb Douglas function enjoys the neoclassical properties listed above.

Once you assume the existence of the aggregate production function Y = F(K, AL), it is clear that the growth of output can be due to growth of A, K, or L.

Solow assumed that A and L grow at *exogenous* rates:

$$\dot{L} = rac{dL}{dt} = nL$$

 $\dot{A} = \gamma A$

At time t = 0, A, and L are given by history. Then one can describe the value of L and A at each point in time:

$$L(t) = L(0)e^{nt}$$

$$A(t) = A(0)e^{\gamma t}$$

So it remains to describe the motion of capital.

Assume K(0) is given by history. The accumulation of capital must follow:

$$\dot{K} = I - \delta K$$

where I denotes investment and δ the depreciation rate of capital.

As usual, investment is assumed to equal savings. The key behavioral equation of the Solow model is that savings equal a constant fraction of output, so:

$$I = sY$$

This completes the description of the model.

A solution is a description of the values of L, A, Y, and K at each point in time.

Now, from the capital accumulation equation:

$$\dot{K} = sY - \delta K$$

= $sF(K, AL) - \delta K$
= $ALsF(K/AL, 1) - \delta K$
= $AL[sF(k, 1) - \delta k]$

Here we have defined k = K/AL.

Define f(k) = F(k, 1), the *intensive* production function. Now we can rewrite the previous equation as:

$$(\dot{K}/K) k = sf(k) - \delta k$$

But k = K/AL implies

$$\dot{k}/k = \dot{K}/K - (n+\gamma).$$

Combine the two to obtain:

$$\dot{k} = sf(k) - (n + \gamma + \delta)k$$

This is the fundamental equation of growth.

$$\dot{k} = sf(k) - (n + \gamma + \delta)k$$

What is the intuition? Capital per effective labor grows faster when there is more investment, hence the role of the savings coefficient *s*. On the other hand, population growth, productivity growth, and faster capital depreciation tend to reduce capital per unit of effective labor.

Obviously once we have solved for the path of k we can obtain K = kAL, and Y. So we can focus on the solution for k.

A steady state is a constant value of k, say k^* , such that $k(t) = k^*$ is a solution of the growth equation.

Hence k^* must solve:

$$sf(k^*) = (n + \gamma + \delta)k^*$$

Example: if the production function is CD, $f(k) = k^{\alpha}$, so:

$$s(k^*)^{\alpha} = (n + \gamma + \delta)k^*$$

that is

$$k^* = \left[rac{s}{n+\gamma+\delta}
ight]^{1/1-lpha}$$

More generally, under the *Inada conditions* $f(0) = 0, f'(0) = \infty, f'(\infty) = 0$ there is a unique nontrivial steady state. This can be shown using the famous Solow diagram. Convergence

The same diagram can be employed to show that k must grow when it is between 0 and k^* , and falls if it is greater than k^* .

Hence the model implies *global* convergence towards the steady state.

What kind of questions can we answer with this model? In general, we can trace the adjustment path to changes in the parameters of the economy (s, δ, n, γ) , or in initial conditions (K(0), L(0), A(0)). We can also modify the model in different ways. In this sense, it is an excellent example of a truly dynamic model.

Example: Starting from steady state, analyze the consequences of a permanent increase in the savings propensity *s*.

In the steady state, however, k is constant. Hence the extensive variables, such as K and Y, grow at the rate $(n + \gamma)$. Per capita variables, such as Y/L, grow at rate γ . But n and γ are exogenous variables in the model. So, in this sense, the model does not explain long run growth.

See Romer, chapter 1, for a discussion.

To illustrate, as Romer also discusses: a permanent increase in the savings rate s has only transitory effects on the growth rate (e.g. a *level effect*, but not a *growth effect*).

The Golden Rule

Another classic question leads to the *Golden Rule*. Suppose that one can choose s. What would an optimal value of s be?

In growth theory, it was proposed to choose *s* so as to maximize *steady state consumption*. Now, in steady state,

$$c = (1-s)f(k)$$

so that the optimal rule would require

$$\frac{dc}{ds} = -f(k) + (1-s)f'(k)\frac{dk}{ds} = 0$$

In steady state, the Solow equation is

$$sf(k) = (n + \gamma + \delta)k$$

so

$$\frac{dk}{ds} = \frac{f(k)}{(n+\gamma+\delta) - sf'(k)}$$

Combining the preceding, we get

$$(1-s)f'(k) = (n+\gamma+\delta) - sf'(k)$$

or

$$f'(k) - \delta = n + \gamma$$

The Golden Rule level of capital is such that the marginal product of capital, net of depreciation, is equal to the growth rate. If k is larger than this level in steady state there is overaccumulation.

The Solow growth equation is an example of a *first order ordinary differential equation*. Such equations are expressed as:

$$\dot{x}(t) = rac{dx}{dt} = g(x(t)), t \in T$$

for some function g. Here $x(t) \in X = R_+$ (the state space) and T is the time interval ([0, ∞) in our Solow discussion) A solution is a function $x : T \to X$ such that x(t) that satisfies the ODE

for each $t \in T$. A steady state is a constant solution, i.e. $x^* \in X$ such that

$$0 = g(x^*)$$

If x^* is a steady state, it is locally a.s. if $g'(x^*) < 0$, and unstable if the inequality is reversed. (Draw *phase diagram* to see why.)

Convergence: suppose *g* is *linear*.

$$\dot{x} = g(x) = ax$$

Any solution is of the form

$$\mathbf{x}(t) = x_0 e^{at}$$

which converges to $x^* = 0$ if a < 0. We then say that x^* is (globally) stable.

For nonlinear g, global convergence is much more involved, but local convergence is simple: If x^* is a steady state, it is locally a.s. if $g'(x^*) < 0$, and unstable if the inequality is reversed. (Draw phase diagram to see why.)